IN THE CLAIMS

Please amend claims 2-3 as follows:

1   1.(Original)   A method of composing an image [IM], the method

2   comprising a step of mapping [MAP] a set of image sample values

3   [SV] from a departure space [DEP] to an arrival space [ARR] in

4   accordance with a geometrical transformation [T], the method

5   comprising the steps of

6   -   computing a zone in the departure space [ITL] by applying

7   the inverse geometrical transformation [T^{-1}] to a zone in the

8   arrival space [TL] covering a group of image samples;

9   -   establishing a group of input values [IV] for the zone in

10 the departure space [ITL], the group of input values [IV]

11 comprising Boolean values [BV], a Boolean input value having a

12 certain position (x_d, y_d) in the departure space and designating the

13 other values having the same position as being non-valid if the

14 position is outside the set of image sample values;

15 -   composing the group of image samples [TL] from the group

16 of input values [IV], the Boolean values [BV] preventing the input

17   values designated as being non-valid from contributing to an image

18   sample.

1   2.(Currently Amended)   A device for composing an image [IM]

2   comprising a processor configured to compose said image by:, the

3   composition comprising a step of

4   -   mapping [MAP] a set of image sample values [SV] from a

5   departure space [DEP] to an arrival space [ARR] in accordance with

6   a geometrical transformation [T]; the device being arranged to

7   perform the steps of

8   -   computing a zone in the departure space [ITL] by applying

9   the inverse geometrical transformation [T^{-1}] to a zone in the

10   arrival space [TL] covering a group of image samples;

11   -   establishing a group of input values [IV] for the zone in

12   the departure space [ITL], the group of input values [IV]

13   comprising Boolean values [BV], a Boolean input value having a

14   certain position (x_d, y_d) in the departure space and designating the

15   other values having the same position as being non-valid if the

16   position is outside the set of image sample values;

17   -   composing the group of image samples [TL] from the group

18   of input values [IV], the Boolean values [BV] preventing the input

19 values designated as being non-valid from contributing to an image

20 sample.

1   3. (Currently Amended)   A computer program product <u>stored on a</u>

2 <u>computer readable medium</u> for an image composition device, the

3 computer program product comprising a set of instructions which,

4 when loaded into the image composition device, cause the device to

5 map [MAP] a set of image sample values [SV] from a departure space

6 [DEP] to an arrival space [ARR] in accordance with a geometrical

7 transformation [T] by performing the steps of

8   -   computing a zone in the departure space [ITL] by applying

9 the inverse geometrical transformation $[T^{-1}]$ to a zone in the

10 arrival space [TL] covering a group of image samples;

11   -   establishing a group of input values [IV] for the zone in

12 the departure space [ITL], the group of input values [IV]

13 comprising Boolean values [BV], a Boolean input value having a

14 certain position (x_d, y_d) in the departure space and designating the

15 other values having the same position as being non-valid if the

16 position is outside the set of image sample values;

17   -   composing the group of image samples [TL] from the group

18   of input values [IV], the Boolean values [BV] preventing the input

19   values designated as being non-valid from contributing to an image

20   sample.